The Design of an Efficient Private Industry

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Abstract

Government-sponsored auctions for production rights (e.g., license auctions, privatizations, etc...) shape the industry structure. Are there mechanisms that induce an efficient industry structure (at least when there are no positive costs to public funds)? The answer is "NO" whenever firms have private information about both fixed and marginal costs. Our analysis also suggests that the second-best industry may either be more competitive or more monopolistic than the first-best one. These insights are in sharp contrast with the ones obtained for models where firms have one-dimensional private information, thus requiring more delicate policy recommendations.

1 Introduction

A government that privatizes a public firm or that sells licenses for production rights affects the market structure of the corresponding industry. What is the best selling strategy for the government? Should the government use auctions, or should it use other, more elaborate mechanisms?

Most economists argue that auctions are particularly desirable in those contexts where the government has little idea about the value of the goods for sale since auctions induce a revelation of valuations through a natural competition mechanism. But, simple auction mechanisms (like the ones practitioners mostly have in mind) are problematic in those contexts in which the auction shapes the ensuing market structure¹.

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¹In particular, flexible auction formats which allow the firms themselves to affect the ensuing market structure may be used to induce more monopolistic market structures which is undesirable from the consumers' viewpoint (see Jehiel-Moldovanu 2000 and 2003).

In this paper we ask whether there exists mechanisms (simple or not) that induce an efficient market structure. There are two firms competing for the right to produce (or to a acquire a privatized firm). The government can either produce itself, or it can award the right to produce to one of the firms, or to both. An important element in the model is that the competing firms have private information that bears both on the fixed cost and the marginal cost associated with future production². Thus, private information is multi-dimensional.

Unlike most of the literature on regulation (see Laffont-Tirole, 1993) we abstract away from the costs of public funds (these inevitably give rise to transferability issues). Thus, we wish to emphasize here that difficulties arise even if frictions due to such costs are absent³. Hence we assume that utility is transferable: the efficiency criterion is defined by the sum of utilities of all agents (including the profits of the firms and the consumer surplus), and transfers do not play a role since their sum (over all participants) adds up to zero.

The previously sketched model closely follows Dana-Spier (DS) (1994) who have analyzed government auctions with an endogenous market structure under the assumptions that 1) firms have one-dimensional private information (either on fixed cost or on marginal cost, but not both) and 2) there are positive costs to public funds, i.e., the government values revenue more than it values consumer of producer surplus. In their model, the first-best can always be achieved if the shadow cost of public funds is equal to one (as assumed here). The main finding of DS (see also Auriol and Laffont, 1992 and McGuire and Riordan, 1995 for similar insights) is that the second-best market structure is more biased toward sole sourcing than the first-best whenever there are positive costs to public funds⁴. The intuition is that biasing the market structure toward sole sourcing is a way to reduce the informational rents of the more efficient firms (since pretending to be less efficient also reduces the chance of being a monopolist).

At first glance, it seems that a procedure based on the well-known Vickrey-Clarke-Groves (VCG) intuition can be used to induce an efficient outcome in our setup in which costs of public funds are absent. But, this argument ignores that VCG insight applies only to the *private values* paradigm (e.g., firms ex-ante have the necessary information needed to calculate their own

²If there were several different kinds of production rights, the structure of the private information could be even more complex.

³It is also unclear to us how large these costs are in practice. Any theory finely relying on these costs must make the case that they are significant.

⁴McGuire and Riordan (1995) obtain this conclusion only when the costs of public funds are not too large, which is presumably a valid assumption in most applications.

expected profits in the various market structure configurations). But the private values paradigm does not apply here: for example, in order to assess the profit in a duopoly configuration, a firm needs to know, say, the marginal cost of the other licensee firm, a piece of information which is usually not available ex-ante. The present set-up is thus one of *interdependent* values.

The VCG insight can be in fact generalized to interdependent values if agents have one-dimensional signals⁵. But, as Jehiel-Moldovanu (2001) have shown, the generalization breaks down if agents have multi-dimensional signals⁶. The consequence for the present model is that *any* mechanism will induce an *inefficient* market structure for some realizations of the parameters.

We also suggest that the optimal second-best industry structure may either be more competitive or more monopolistic than the first-best, depending on the distribution of incomplete information and payoff specifications.

The rest of the paper is organized as follows. In Section 2 we present the formal model, which is similar to the one analyzed by DS (1994), except for the multi-dimensional private information and the absence of costs to public funds. In Section 3 we state our main result. In Section 4 we provide a further discussion about the links to the existing literature.

2 The Model

Our model parallels that of DS (1994) with two essential differences to be outlined below.

For simplicity, we assume that there are only two⁷ firms (or bidders). Each bidder i privately observes a two-dimensional signal $\theta_i = (F_i, c_i)$ that reflects its cost structure: F_i is a fixed cost and c_i is the marginal cost. In contrast, DS assume that the private information is one-dimensional (the authors distinguish according to whether this one-dimensional private information is the fixed cost or the marginal cost, but they do not allow the private information to bear on both).

The signals θ_1 and θ_2 are independently distributed on $[\underline{F}, \overline{F}] \times [\underline{c}, \overline{c}]$

⁵See Jehiel-Moldovanu 2001 for a social choice setup allowing also for allocative externalities, and Maskin 1992, Dasgupta-Maskin 2000 for simple auction setups.

⁶Maskin (1992) exhibits a one object auction example where bidders have twodimensional private signals about the object and he shows that no efficient mechanism exists. The reason for Maskin's result is however different from that in the present paper: bidders care only about one alternative (where they get the object), but have a twodimensional signal about it. But any mechanism can only condition on a one-dimensional sufficient statistic.

⁷Our insights obviously carry over to more general settings.

with continuously differentiable density functions⁸. We let $\pi^{m,i}(\theta_i)$ denote firm i's profit if it is awarded a sole production right (monopoly/sole source). This profit function is independent of θ_{-i} because in this case only the cost structure of firm i determines its ensuing profit. We let $\pi^{d,i}(\theta_1,\theta_2)$ denote firm i's profit if both firms are awarded production rights (duopoly/dual-source). This profit function generally depends on θ_{-i} , at least through c_{-i} (for example, think of Cournot competition in a market for a homogenous good). Finally, we assume that a firm earns zero profits if it is not awarded a production right⁹.

Consumer surplus depends on the market structure and on the cost structure of the firms involved. Accordingly, we let $S^{m,i}(\theta_i)$ denote the consumer surplus when firm i is the sole producer, and let $S^d(\theta_1, \theta_2)$ denote this surplus when both firms produce¹⁰.

The government has the option to produce itself with cost parameter $\theta_q = (F_q, c_q)$, assumed to be common knowledge.

Overall, there are four possible alternatives referred to as k = 1, 2, d, g:

- Sole-source (firm i = 1, 2) with associated welfare $W^{i}(\theta_{i}) = S^{m,i}(\theta_{i}) + \pi^{m,i}(\theta_{i})$
- Dual-source with associated welfare $W^d(\theta_1, \theta_2) = S^d(\theta_1, \theta_2) + \pi^{d,1}(\theta_1, \theta_2) + \pi^{d,2}(\theta_1, \theta_2)$
- Government production with associated welfare $W^g(\theta_g)$ (this term already includes consumer surplus in this alternative)

We assume that the social planner's objective is to maximize expected welfare which is given by:

$$W = E[\sum_{i} \pi_i + S]$$

where S denotes the consumer surplus and π_i the profit of firm i. Possible transfer payments t_i from bidder i to the government do not enter the social planner's criterion because we assume that there are no costs of public funds.

⁸We do not need to assume that the distributions are symmetric.

⁹We make this assumption to keep as close as possible to the model of Dana and Spier (1994). In a number of applications this is a rather restrictive assumption. For example, if one of the firms is an incumbent who produces in a related market, the assumptionm is not met. In such cases, the participation constraint is itself affected by the mechanism (see Jehiel, Moldovanu, and Stacchetti, 1996 and 1999).

¹⁰Like DS (1994), we do not assume that the designer has to elicit the information about the demand function. Clearly, our insights carry over to the more plausible setting in which the designer needs not have private information about demand.

In contrast, DS (1994) assume that the government maximizes

$$W = E[\sum_{i} \pi_i + S + (\lambda - 1) \sum_{i} t_i]$$

where $\lambda > 1$ represents the shadow cost of public funds. This is another essential difference (other than dimensionality) between DS (1994) and our paper¹¹.

By the revelation principle, there is no loss of generality in restricting attention to direct revelation mechanisms where agents report truthfully in equilibrium. Such mechanisms can be described as follows: Each bidder i makes an announcement $\widehat{\theta}_i$ about his two-dimensional signal. Based on the profile of announcements, $(\widehat{\theta}_i, \widehat{\theta}_{-i})$, the designer chooses an allocation $p^k(\widehat{\theta}_i, \widehat{\theta}_{-i})$ and a transfer $t_i(\widehat{\theta}_i, \widehat{\theta}_{-i})$, where for each profile of reports $(\widehat{\theta}_1, \widehat{\theta}_2)$, $p^k(\widehat{\theta}_i, \widehat{\theta}_{-i})$ is the probability that alternative k is chosen, and $t_i(\widehat{\theta}_i, \widehat{\theta}_{-i})$ is the transfer from firm i to the designer.

Let

$$\Pi_i(\widehat{\theta}_i \mid \theta_i) = E_{\theta_{-i}}[p^i(\widehat{\theta}_i, \theta_{-i})\pi^{m,i}(\theta_i, \theta_{-i}) + p^d(\widehat{\theta}_i, \theta_{-i})\pi^{d,i}(\theta_i, \theta_{-i}) - t_i(\widehat{\theta}_i, \theta_{-i})]$$

Truthful revelation requires that:

For all
$$\theta_i$$
, $\widehat{\theta}_i$, $\Pi_i(\theta_i \mid \theta_i) \ge \Pi_i(\widehat{\theta}_i \mid \theta_i)$ (1)

The participation constraints require that:

For all
$$\theta_i$$
, $\Pi_i(\theta_i \mid \theta_i) \ge 0$ (2)

The designer's optimization problem is

$$\max_{p^k} E_{\theta_1,\theta_2} \left[\sum_{k=1,2,d,g} p^k(\theta_i,\theta_{-i}) W^k(\theta) \right]$$
(3)

subject to the incentive constraints (1) and to the participation constraint (2).

Because we assume that there are no costs to public funds, it is readily verified that the participation constraints are never binding in our context. To see this, observe that the welfare criterion as well as the incentive constraints are unaffected if all transfers $t_i(\hat{\theta}_i, \hat{\theta}_{-i})$ are reduced by a fixed term T. By choosing T sufficiently large we can get rid of the participation constraints. Thus, the designer's problem reduces to maximizing (3) subject to the incentive constraints (1).

¹¹In DS's model if $\lambda = 1$ the designer can obtain the first-best.

3 The Main Result

It is rather difficult to characterize the solution to the program defined in the previous Section 2. However, a simple point can be addressed. The firstbest industry structure requires choosing a market structure $k^*(\theta_i, \theta_{-i}) \in$ $\arg\max_k W^k(\theta_i,\theta_{-i})$ for each realization of (θ_i,θ_{-i}) . Clearly, if such an allocation rule were implementable it would be the solution to the designer's problem. But, as the following Proposition shows, such an allocation rule cannot be implemented:

Proposition 1 For generic profit functions $\pi_i^{m,i}(\theta_i)$ and $\pi_i^d(\theta_i,\theta_{-i})$ and for generic distributions of signals, any implementable industry structure is inefficient with positive probability.

The fundamental reason behind the above result is that the incentive constraints impose much more stringent conditions when the type space is multidimensional than when it is one-dimensional. While in the one-dimensional case, incentive constraints generally translate into a monotonicity conditions on the interim allocation rule (see for example the classical analysis in Myerson, 1981), in the multi-dimensional case an additional integrability constraint appears. This constraint forces some identities that cannot hold generically for the efficient allocation rule. To understand this point, let $V_i(\theta_i) = \Pi_i(\theta_i \mid \theta_i) = \max_{\widehat{\theta}_i} \Pi_i(\widehat{\theta}_i \mid \theta_i)$ denote the equilibrium interim expected utility of bidder i with type $\theta_i = (F_i, c_i)$. Under mild assumptions¹², the envelope theorem can be invoked to infer that ¹³:

$$\frac{\partial V_i(\theta_i)}{\partial F_i} \equiv E_{\theta_{-i}}[p^i(\theta)\frac{\partial \pi^{m,i}(\theta_i)}{\partial F_i} + p^d(\theta)\frac{\partial \pi^{d,i}(\theta)}{\partial F_i}] \qquad (4)$$

$$\frac{\partial V_i(\theta_i)}{\partial c_i} \equiv E_{\theta_{-i}}[p^i(\theta)\frac{\partial \pi^{m,i}(\theta_i)}{\partial c_i} + p^d(\theta)\frac{\partial \pi^{d,i}(\theta)}{\partial c_i}]$$

But, at any point of differentiability, V_i must have equal cross-derivatives:

$$\frac{\partial}{\partial c_i} \left[\frac{\partial V_i(\theta_i)}{\partial F_i} \right] \equiv \frac{\partial}{\partial F_i} \left[\frac{\partial V_i(\theta_i)}{\partial c_i} \right] \tag{5}$$

This means that

$$\frac{\partial}{\partial c_{i}} E_{\theta_{-i}}[p^{i}(\theta) \frac{\partial \pi^{m,i}(\theta_{i})}{\partial F_{i}} + p^{d}(\theta) \frac{\partial \pi^{d,i}(\theta)}{\partial F_{i}}] =$$

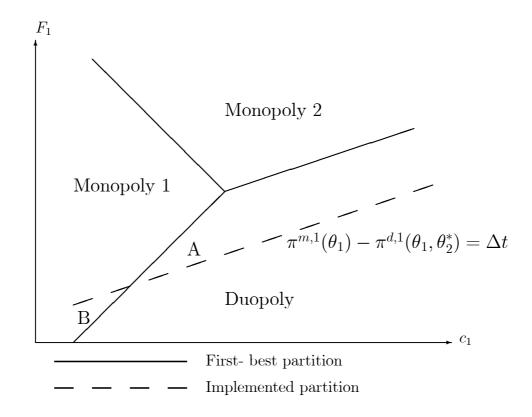
$$\frac{\partial}{\partial F_{i}} E_{\theta_{-i}}[p^{i}(\theta) \frac{\partial \pi^{m,i}(\theta_{i})}{\partial c_{i}} + p^{d}(\theta) \frac{\partial \pi^{d,i}(\theta)}{\partial c_{i}}]$$
(6)

¹²See Milgrom-Segal (2002) for the weakening of the required standard assumptions. ¹³Note that $\frac{\partial \pi^{m,i}(\theta_i)}{\partial F_i} = \frac{\partial \pi^{d,i}(\theta)}{\partial F_i} = -1$ if F_i is a separable fixed cost.

The identity in (6) imposes a relation that involves the allocation rule $p^k(\theta)$ and the payoff functions $\pi^{m,i}(\theta_i)$, $\pi^{d,i}(\theta)$. Note that the efficient allocation rule is completely determined except on measure zero of events where the designer is indifferent between two or more alternatives, and that it clearly depends on the consumer surplus induced by each market structure. Thus, for generic values of the profit functions, there is no hope that the efficient allocation rule be compatible with identity 6 since that identity is independent of the consumer surplus. The impossibility result follows.

To get more intuition for the result, it is instructive to consider the simpler case where only firm 1 has private information. That is, the type θ_2^* of firm 2 is assumed to be common knowledge.

The figure below depicts the corresponding partition of the (F_1, c_1) type space in areas where each possible market structure is efficient¹⁴.



¹⁴To simplify, we assumed here that only alternatives k = 1, 2 and d can be efficient.

Any mechanism sets a fixed transfer t^k for each possible alternative, and lets bidder 1 choose his preferred alternative given these transfers¹⁵.

Consider types θ_1 on the boundary between the regions where sole production by firm 1 and dual production are efficient. This boundary is defined by the following system:

$$S^{m,1}(\theta_1) + \pi^{m,1}(\theta_1) = S^d(\theta_1, \theta_2^*) + \pi^{d,1}(\theta_1, \theta_2^*) + \pi^{d,2}(\theta_1, \theta_2^*)$$
 (7)

$$S^{m,1}(\theta_1) + \pi^{m,1}(\theta_1) \ge S^{m,2}(\theta_2^*) + \pi^{m,2}(\theta_1^*)$$
 (8)

The equality above is equivalent to

$$\pi^{m,1}(\theta_1) - \pi^{d,1}(\theta_1, \theta_2^*) = S^d(\theta_1, \theta_2^*) - S^{m,1}(\theta_1) + \pi^{d,2}(\theta_1, \theta_2^*) \tag{9}$$

On the other hand, for the efficient industry structure to be implementable, any type θ_1 on the boundary must be indifferent between sole and dual production:

$$\pi^{m,1}(\theta_1) - t^1 = \pi^{d,1}(\theta_1, \theta_2^*) - t^d \tag{10}$$

In other words, there should be a constant $\Delta t = t^1 - t^d$ such that

$$\pi^{m,1}(\theta_1) - \pi^{d,1}(\theta_1, \theta_2^*) = \Delta t \tag{11}$$

The impossibility result follows by noting that equations (9) and (11) cannot be compatible with each other for arbitrary functions $S^d(\theta_1, \theta_2^*)$, $S^{m,1}(\theta_1)$, and $\pi^{d,2}(\theta_1, \theta_2^*)$.

4 Discussion

Even if there are no costs to public funds, the first-best cannot be achieved in our model. It is then natural to ask how the second-best market structure is biased relative to the first-best.

As in most multi-dimensional incentive problems, it is very hard to characterize the second-best, and more work is needed to derive sharper characterizations. However, there is no reason why the market structure should

¹⁵This is a version of the so called *taxation principle*, and is the mere translation of the incentive constraints in the principal-agent problem.

be biased toward sole sourcing (a result that was obtained in the simpler one-dimensional models)¹⁶.

For example, consider the case considered at the end of the previous Section where only firm 1 has private information. Recall that any feasible mechanism sets a transfer t^k for each possible alternative, and then lets firm 1 choose her preferred alternative given these transfers.

As Figure 1 illustrates, for any values of t^k , the implemented market structure is biased toward sole sourcing for types θ_1 lying in region A and it is biased toward dual sourcing for types θ_1 lying in region B. The aggregate bias will obviously depend on functions governing the distribution of type θ_1 , and cannot generally be one-sided as in the one-dimensional models considered in the earlier literature.

Implicitly, we have considered so far static one-shot mechanisms in which the allocation rule and the transfers are decided at the same time. As long as bidders' information remains the same throughout a possibly sequential mechanism, our impossibility result applies¹⁷. Things change however if bidders acquire further information during the interaction. In a recent paper, Mezzetti (2002) considers an interdependent valuation setup in which bidders get to observe (for free) their payoff in the chosen social alternative before monetary transfers are made. He observes that the efficient allocation can be implemented in a two-stage mechanism: in stage 1 bidders reveal their private information which is solely used to implement the efficient alternative; in stage 2, each bidder is asked to report his payoff (assumed to be known to the bidder by then) and transfers are then made according to the Vickrey-Clarke-Groves rule, i.e., each bidder receives a transfer which is, up to a constant, equal to the sum of other bidders' reported payoffs¹⁸.

We wish to point out here that bidders' incentives to reveal truthfully their payoffs in stage 2 of Mezzetti's mechanism are virtually non-existent since bidders are completely indifferent as to which payoff to report: the alternative has been chosen already, and their transfer only depends on the reports of others. This suggest that such mechanisms are not appealing from a practical viewpoint¹⁹. This finding should be contrasted with the original

¹⁶In the multi-dimensional setup it is not a priori clear which incentive constraints are binding (and it is thus even less clear how to bias the allocation rule in order to relax the incentive constraints).

¹⁷Because, roughly speaking, the incentive constraints apply to the normal form representation of a possibly multi-period mechanism.

¹⁸Since bidders know their own payoff this is very much like a private value setting, and efficiency can be accordingly achieved.

¹⁹It might even be argued that malicious bidders have incentives to distort their reports in order to hurt competitors.

insight of the Vickrey-Clarke-Groves mechanisms where the incentives to report truthfully are, except in degenerate cases, strictly positive (think of the second-price auction in a private value setting; there truth telling is forced by the still to be resolved uncertainty about who will be the actual winner).

Finally, note that schemes in which transfers are postponed until all information is available (think about a license auction where the license fees are payed after the profits from operation have been already realized) are also very sensitive to renegotiation pressures and moral hazard. Most practitioners are well aware of these dangers.

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